



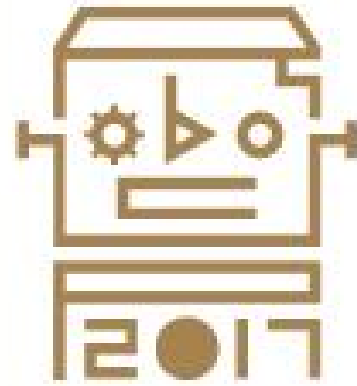
RoboCup  
Junior  
China



2019

RoboCup Junior

Onstage

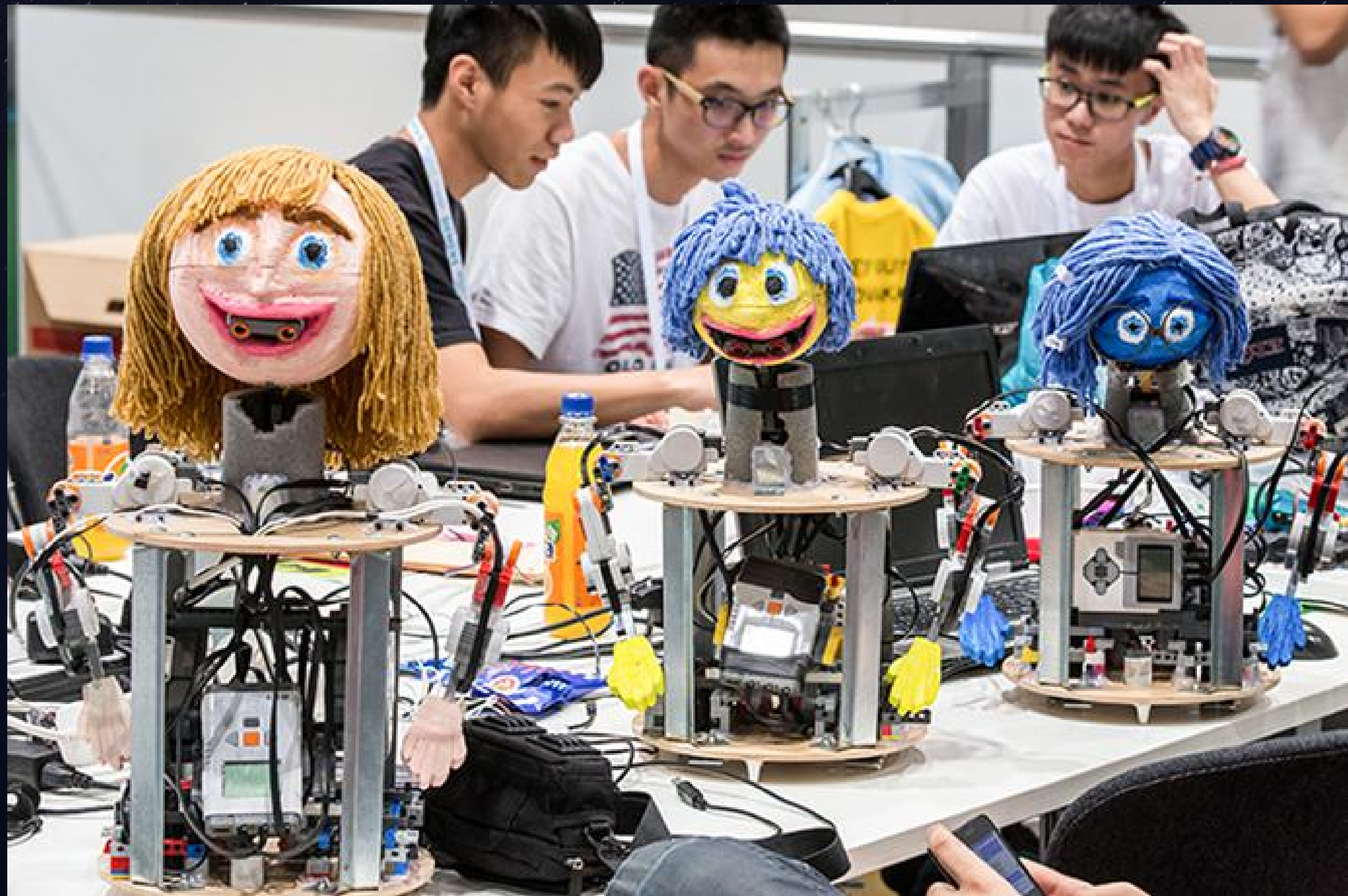


**RoboCup 2017**  
Nagoya Japan



**RoboCup 2018**  
MONTRÉAL · CANADA

**2019**  
**Australia**  
**Sydney**



LHEN-Dance

Peru

filmora FILM



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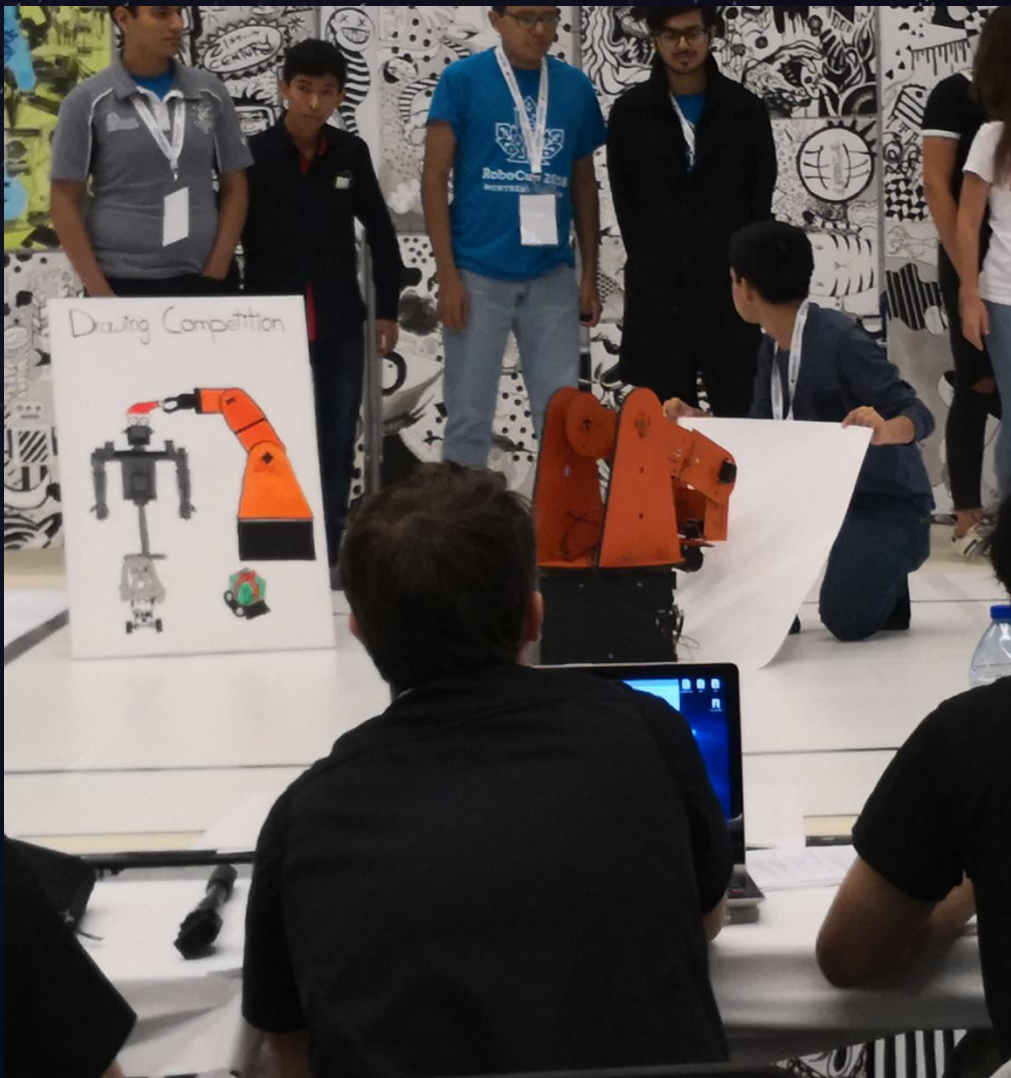
# 2018RoboCup国际机器人大赛蒙特利尔ONSTAGE大家庭的合影

初级组25队 高级组20队 共45个队伍参赛









# 2018 Onstage 规则修改

取消按年龄分组，

改为按照是否具有参赛经验分组。

✓最小的年龄是13岁，参与学生的年龄为13-19岁。

✓一支参赛队应至少有2名成员，足球和救援赛的成员总数不应超过4名，舞蹈不超过5名。

**Onstage Preliminary**  
舞蹈初级组

**Onstage Advanced**  
舞蹈高级组

Team	Team members	Eligibility
Team A		 Preliminary  Advanced
Team B		 Preliminary  Advanced
Team C		 Preliminary  Advanced
Team D		 Preliminary  Advanced
Team E		 Preliminary  Advanced

## 舞蹈初级组

- 可以允许跟着线路走或者在线路上铺地纸（垫子）

## 舞蹈高级组

- 需要使用更先进的技术或特定技术（传感器，图像识别等）的挑战和任务。

# 舞蹈竞赛组成





➤5分钟的舞台技术演示。团队分工请看看；传感器系统；自主开发的机器人功能，例如人机交互、机机交互；机器人没有服装以便展示所使用的技术和关键特征... ..

➤15分钟的技术面试。根据技术标准进行机器人的编程评判；创新的技术会得分更高；学生对所使用的机器人技术的理解，展示真实性和原创性；准备好回答机器人设计的技术方面的问题... ..

➤1-2分钟的舞台表演。创意性、创新性、娱乐性、原创性... ..

➤技术档案：在竞赛前三周提交（2-4页），解释所使用的机器人硬件，软件，通信和算法... ..

Category	Mark
<p><b>Presentation of fully working robotic system.</b> More complex robotic systems will score higher marks. For example: 0-5 for a fully working but simple robotic system (kit based), 5 to 10 for a fully working robotic system with a range of sensors/actuators, 10 to 15 for fully working robotic system built from scratch including the electronics.</p>	/10
<p><b>Robot capabilities demonstrated in the presentation (hardware, software, sensors, algorithms, mechanical engineering, electronics, and communication).</b></p> <p>For example: 0-5 for basic capabilities with simple sensor/actuator feedback loops, 5 to 10 for integrating hardware/software in more interesting ways to create the robotic capabilities, 10 to 15 innovative and creative robotic features combined to create unusual robotic capabilities.</p>	/8
<p><b>Clarity and quality of the presentation.</b></p> <p>For example: 0 to 1 for presentation which is difficult to follow and does not show robot capabilities, 2 to 3 effective presentation where most of capabilities of the robot are clearly explained, 4 to 5 Presentation clearly demonstrates all the robot capabilities are professionally presented by the team.</p>	/5
<p><b>Concept and technical innovation</b></p> <p>Marks awarded for the project idea in terms in a technically unusual, creative or ambitious concept for the robots and robotic performance.</p>	/7
<p><b>Total Score</b></p>	/30



Category	Examples of how high marks may be achieved are:	Mark
Programming	<ul style="list-style-type: none"> <li>• Efficient programming</li> <li>• Advanced programming (optimized, elegant)</li> <li>• Innovative programming solutions</li> <li>• Development of libraries (as distinct from functions)</li> <li>• Machine Learning</li> <li>• Ability to explain how the program works and interactions between the hardware and software</li> <li>• Ability to explain why programming decisions were made, choice of programming languages, and any difficulties with the software</li> </ul>	/ 7
Mechanical Hardware	<ul style="list-style-type: none"> <li>• Mechanical systems that are <b>Reliable / Complex / Innovative</b></li> <li>• Mechanisms that have been developed for very high precision, or for mechanically 'difficult' situations</li> <li>• Advanced and functional arms/hands/faces</li> <li>• The robot has the ability to manipulate objects</li> <li>• The robot can move on any terrain</li> <li>• Automatic balance system</li> <li>• Appropriate actuators used</li> <li>• Ability to explain how the mechanical</li> <li>• Ability to explain why decisions were</li> </ul>	

Electronic Hardware	<ul style="list-style-type: none"> <li>• Some of the electronics have been custom than offered in the market</li> <li>• Innovative use and integration of sensors</li> <li>• Useful GPS, gyroscope and accelerometers</li> <li>• Innovative use of technologies to aid in power source (hydrogen, solar), holography</li> <li>• Ability to explain how the electronics</li> <li>• Ability to explain why decisions were made</li> </ul>
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Robotic Communication & Interaction	<ul style="list-style-type: none"> <li>• Useful robotic communication</li> <li>• Useful vision recognition</li> <li>• Useful voice recognition</li> <li>• The robot has the ability to talk</li> <li>• Development of communication architectures</li> <li>• Sensors used to achieve robot-robot interaction, for example robots following robots</li> <li>• Sensors used to achieve robot-human interaction</li> <li>• Ability to explain how and why the communication is occurring</li> </ul>	/ 7
<b>Deductions (at discretion of judges – up to 15 marks each)</b>	<ul style="list-style-type: none"> <li>• <b>Judges should satisfy themselves that this is the work of the students</b></li> <li>• <b>Originality of robot software and hardware (no reuse from previous competitions)</b></li> <li>• <b>Team members are able to discuss their technical involvement with the robot</b></li> </ul>	
<b>Total Score</b>		<b>/30</b>

Category	Examples of how high marks may be achieved are	Mark
Quality of the Whole Performance	<ul style="list-style-type: none"> <li>• There is a link, or common theme demonstrated in the whole performance. The idea of the performance is well understood.</li> <li>• A performance that is engaging throughout</li> <li>• Ambitious use of the stage area</li> <li>• Home-built robot costumes complement the performance and are engaging</li> <li>• Original and innovative performance</li> </ul> <p><u>Only robots and up to two performers are allowed on stage</u></p> <p><u>Use of props or scenery on the stage is allowed only when used for interaction with the robot.</u></p>	/ 12
Robot's Movements	<ul style="list-style-type: none"> <li>• Non-repetitive robot movements and/or a varied robot performance</li> <li>• Reliable robots that do not fall apart and work as expected for the duration of the performance</li> <li>• Risky movements by robots (e.g. Robot(s) can balance itself)</li> <li>• Fluid movements similar to humans</li> <li>• Robot(s) moves around the whole stage area</li> <li>• A slick and polished performance throughout the display</li> <li>• Robot movement(s) are choreographed tightly to the music.</li> </ul>	/ 12
Effective Use of Technologies	<ul style="list-style-type: none"> <li>• All sensors are used and add value to the performance</li> <li>• Technologies are used in new or different ways not seen before</li> <li>• Unusual technol or power system</li> <li>• Effective use of a recognition etc.)</li> <li>• A digital display</li> </ul>	
Communications & Interactions	<ul style="list-style-type: none"> <li>• Communication</li> <li>• Human-robot int</li> <li>• Robot-robot inte</li> <li>• Synchronization</li> <li>• Interaction betw</li> <li>• Robot(s) can avo</li> </ul>	

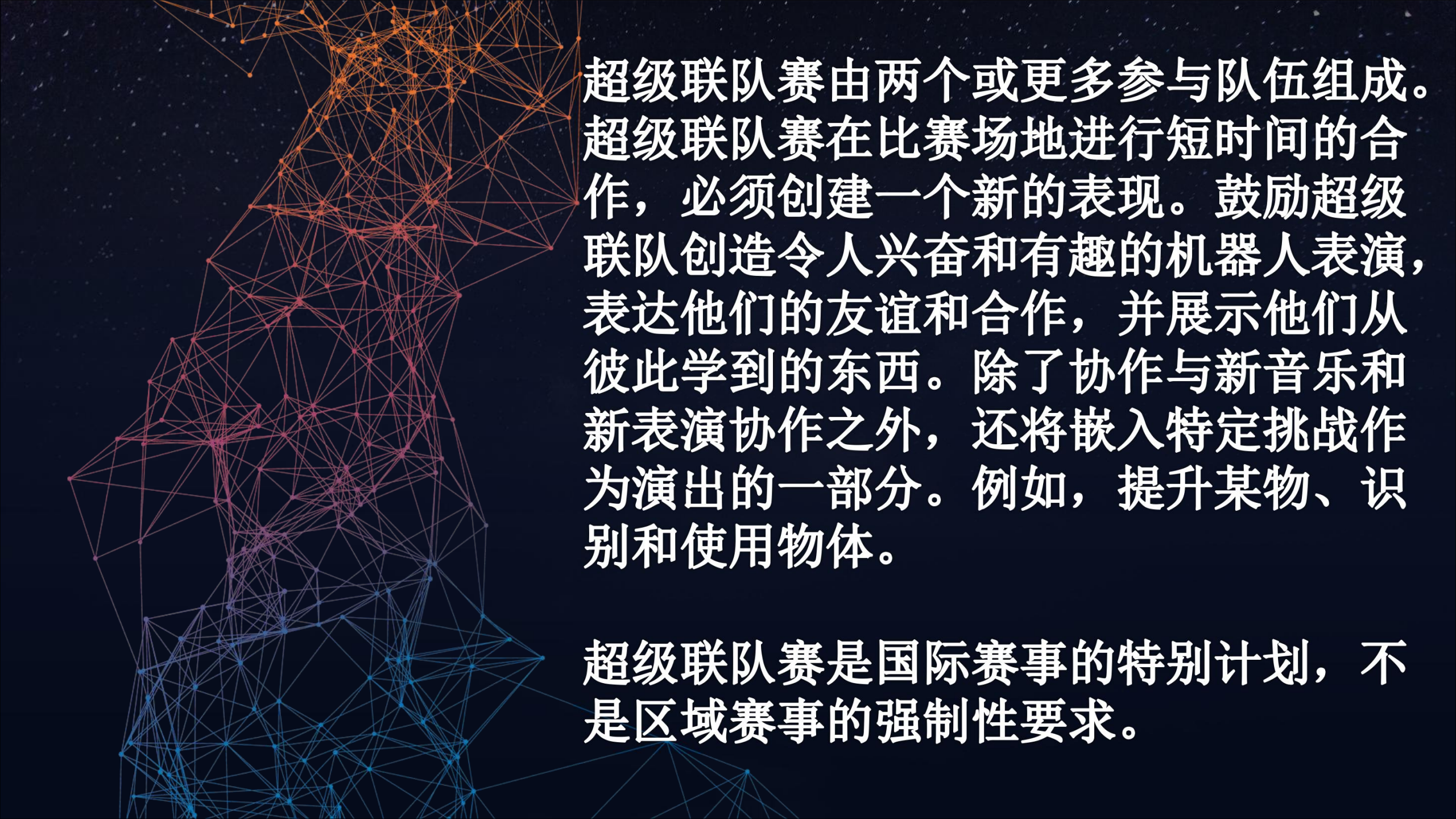
无计划的人为干预: -3  
 重新启动: 每次重新启动  
 -5  
 时间控制: 每10秒超过-3  
 出界: 每次出界-3  
 应当警告违反规则的团队  
 在第二次演出中不允许此类犯规, 并由裁判自行决定适当扣除。

<b>Deductions</b>	<ul style="list-style-type: none"> <li>• Each unplanned human intervention: -3</li> <li>• Restarts: -5 for each re-start</li> <li>• Allotted time: -3 for each 10 seconds over</li> <li>• Within area: -3 for each infraction of the boundary</li> </ul> <p><i>Teams that infringe the rules should be warned that such infringements will not be allowed in the second performance and marks deducted appropriately at the judge's discretion.</i></p>	
<b>Total Score</b>		/40



# Super Team Performance

## 超级联队赛



超级联队赛由两个或更多参与队伍组成。超级联队赛在比赛场地进行短时间的合作，必须创建一个新的表现。鼓励超级联队创造令人兴奋和有趣的机器人表演，表达他们的友谊和合作，并展示他们从彼此学到的东西。除了协作与新音乐和新表演协作之外，还将嵌入特定挑战作为演出的一部分。例如，提升某物、识别和使用物体。

超级联队赛是国际赛事的特别计划，不是区域赛事的强制性要求。

# RCJ中国赛改革设想

舞蹈  
基础组

舞蹈  
标准组

# 项目设置

舞蹈  
基础组

小学组（1-6年级）

中学组（7-12年级）

技术面试（20分）

两轮表演（40分/轮）



# 项目设置

舞蹈  
标准组

初级组 (10-13岁)

高级组 (13-19岁)

(国际赛名额)

日志 10%

笔试 10%

(技术面试 10%、技术展示  
20%、两轮表演共40%、超  
级联队 10%)



项目负责人  
TC组

# 组织机构



传说 Legend of  
有这样一份 The JOB  
工作！

无工资、无补贴、无五险一金  
有压力、有风险、有争议指责

- ◆ 打分透明，及时公布；
- ◆ 裁判轮换，打分复审；
- ◆ 服从安排，禁止攻击；
- ◆ 论坛分享，技术共进；
- ◆ 增设一些技术奖或创意奖；
- ◆ ... ..

欢迎大家提出宝贵建议！



T H A N K   Y O U